

QUALIFYING EXAMINATION

DIFFERENTIAL GEOMETRY

September 13, 2004

A C^∞ manifold is a Hausdorff topological space with a countable basis which is equipped with a C^∞ structure.

Answer any six questions.

1. Prove that the set of 2×2 matrices of rank one is a three-dimensional submanifold of the space $M(2, \mathbb{R})$ of all 2×2 matrices with real entries.
2. Prove that every paracompact C^∞ manifold carries a C^∞ Riemannian metric.
3. Consider the unit 2-sphere $\mathbb{S}^2 \subset \mathbb{R}^3$. Let x, y and z be the restrictions of the coordinate functions of \mathbb{R}^3 to \mathbb{S}^2 . Prove that

$$dx = \frac{-ydy - zdz}{x}$$

and compute $\int_\gamma (dx + dy + dz)$ where γ is a curve connecting $(0,1,0)$ to $(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}})$.

4. Let M be a C^∞ manifold and $f : M \rightarrow \mathbb{R}$ a smooth function.
 - (a) Suppose $df_x \neq 0$ at every point where $f(x) = 0$. Prove that $N = f^{-1}(0)$ is a smooth submanifold of M of codimension one.
 - (b) Prove that if M and f are as above and M is orientable, then N is orientable. *Hint:* Use a Riemannian metric if you like.
5. Show that that the real projective plane \mathbb{RP}^2 is a submanifold of \mathbb{R}^4 .
Hint: Let $f : \mathbb{S}^2 \rightarrow \mathbb{R}^4$ be the map defined by

$$f(x, y, z) = (x^2 - y^2, xy, xz, yz).$$

Show that f factors through a mapping $g : \mathbb{RP}^2 \rightarrow \mathbb{R}^4$. Then show that g is an embedding.

6. Let $f : M \rightarrow N$ be a C^∞ map between C^∞ manifolds, where M is compact. Define a regular value of f . Show that the cardinality of the set $\{f^{-1}(y)\}$ where y ranges over the regular values of f defines a locally constant finite function.
7. Find the geodesics of
- (a) the n -sphere S^n .
 - (b) the right circular cylinder $\{(x, y, z) \mid x^2 + y^2 = 1, z \in \mathbb{R}\}$.
- Explain.
8. Prove Gauss' Lemma that states that in the geodesic ball around a point p in a Riemannian manifold, the geodesic segments through p are the orthogonal trajectories of the hypersurfaces $\{\exp_p(v) \mid |v| = \text{const}\}$.
9. By using polar coordinates on the 2-sphere $S^2 \subset \mathbb{R}^3$, show that S^2 is orientable.
10. Suppose that $a(z), b(z)$ are real C^1 functions defined on an interval I . Let x, y denote the standard coordinates on \mathbb{R}^2 . Consider the vector fields on $\mathbb{R}^2 \times I$, $z_1 = \frac{\partial}{\partial x}$ and $z_2 = a(z)\frac{\partial}{\partial x} + b(z)\frac{\partial}{\partial y}$. Prove that the distribution spanned by z_1 and z_2 is integrable if and only if there exists a real constant A such that $a = Ab$.